

SOLEIL New Platform for Fast Orbit Feedback

Romain BRONÈS, A. Bence, J. Bisou, N. Hubert, D. Pédeau, G. Pichon Sept. 11Th 2023 - IBIC





- Context and specifications
- New platform insight and installation
- Test results
- New identification features







Context and specifications



Synchrotron SOLEIL

3rd generation light source

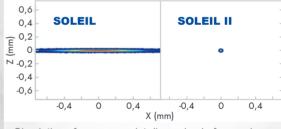
- In operation since 2006
- France, 20km south of Paris
- 29 Beamlines in operation

Upgrade to SOLEIL II

- 4th generation
- TDR ongoing
- Shutdown scheduled for mid-2027
- Lower emittance (< 100 pm.rad)



Energy	2.75 GeV
Circumference	355 m
Revolution period	1,18 µs
Number of cells	16
Beamlines	29



Simulation of a source point dimension before and after the upgrade



Context and specifications

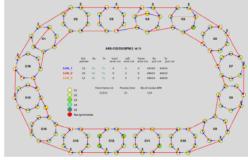
- Upgrade obsolete BPM electronics ahead of SOLEIL upgrade
- Move FOFB application out of the BPM electronics
- Toward a very flexible platform: follow years of evolutions.

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Current BPM electronics: Libera electron



Current PSC: Itest BILT (correction magnet) Power Supply Controller



Schematic of the current BPM dedicated network

	Evolution	Impact
2024	FOFB running on new platform	Same performances
2025	Added features	Faster lattice identification.
2026	New BPM electronics	Loop latency reduced, data rate increased, correction bandwidth increased
2028	SOLEIL II, new PSC	Loop latency reduction, dimension reduction, SOLEIL II performances
2028 +	New correction algorithm	Increased performances

1		Actual FOFB	Future FOFB
ć	# BPM	122	180~200
	# Corrector	50 H & V	44~60
-	Data rate	10 kHz	100 kHz
2	Correction BW	200 Hz	1 kHz
	Loop Latency	350 μs	100µs
1	Stability	10 % of beam size 20 μm Η ; 0.8 μm V	2-3% of beam size 50 nm H & V

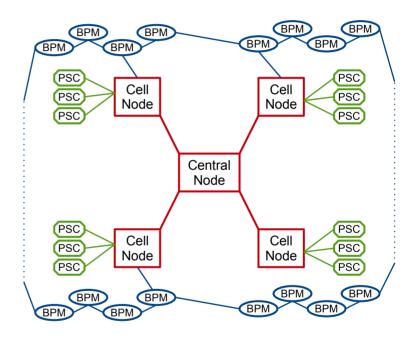




New platform insight and installation

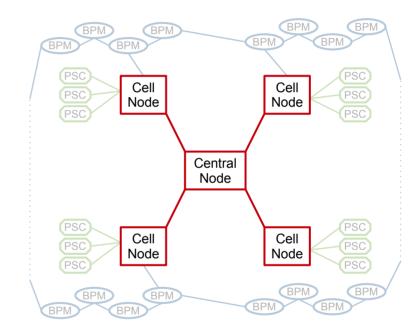


- New platform: 5 Node systems connected in a star topology
- 122 BPMs
- 100 PSCs





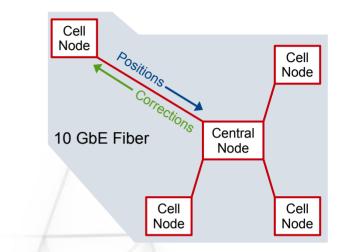
Central & Cell Nodes





Central & Cell Nodes

- Node system: MTCA chassis Main part: SoC-FPGA AMC board
- Connected by dedicated fibers, SFP module connected to FPGA
- Position and Correction packets inside Ethernet frames, 10 Gbps
- One frame up-down transfer per loop cycle (10 kHz for current BPMs)
- Measured up-down latency < 4,5 μs

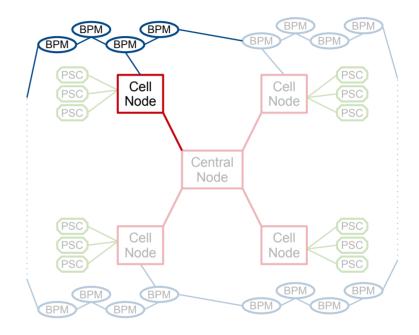




MTCA chassis Node (front and back)



BPM position grabbing





BPM position grabbing

- Each Cell Node connected to BPM dedicated • communication ring (DLS Communication Controller)
- Copper wire SFP module, read only connection •
- Capture and forward position data of $\frac{1}{4}$ (~30) of the BPMs
- Group of position numbered (loop iteration number)

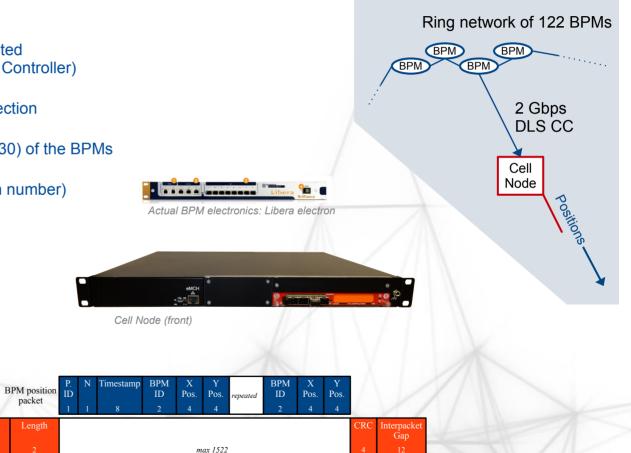
Start Frame

Delimiter

ETH

L1/L2

Destination



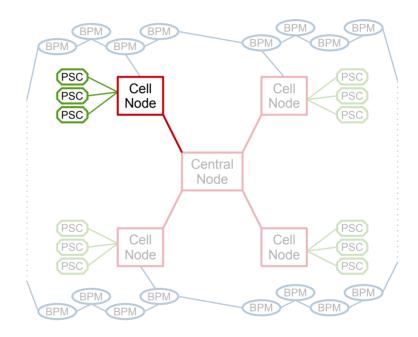
Source

packet

Length



Correction transmission





Correction transmission

- Each Cell Node connected ¼ (~25) PSC in local cell cabinet and three neighbouring cells
- Regular RJ45-CAT6 cable, RS422 UART 1.25 Mbps 4 link pairs per cable, 80m max.
- CACTUS: Custom RTM with 32 TX drivers To be decommissioned with the PSC for SOLEIL II.
- Quick PSC driver switching: current/new platform Electromechanical relays, powered from central location.

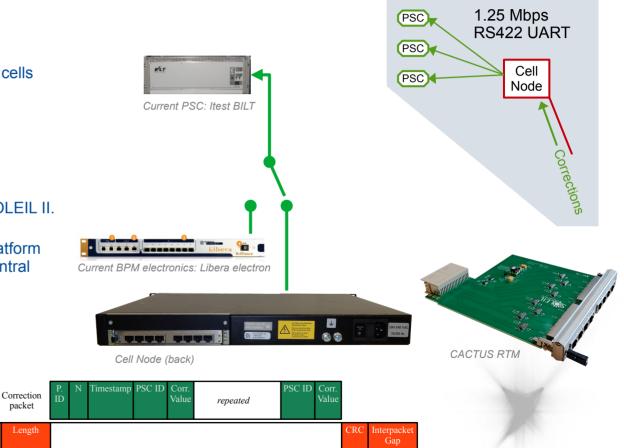
Preamble

ETH

L1/L2

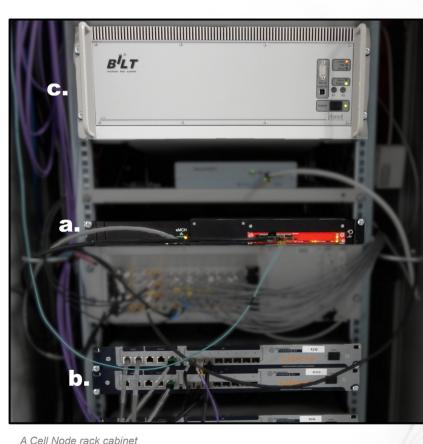
Start Frame Destination

Delimiter



max 1522





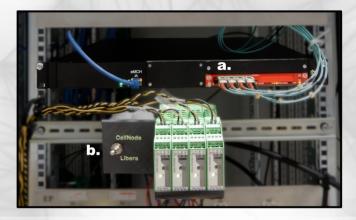
a. Cell Node with fiber connection to Central Node and copper connection to BPMs.

Connections to PSC on the back, not seen.

b. BPM electronics.

c. Power Supply Controller.

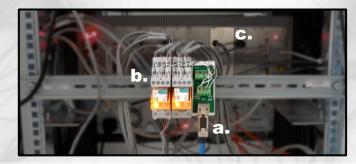
Installation pictures



Central Node rack cabinet

a. Central Node with outgoing fiber to CellNodes

b. Switch lever and power supplies to relays



A cell rack cabinet

a. Incoming RJ45 CAT6 cable from a Cell Node going to a breakout panel b. Electromechanical relays. Inputs from RJ45 breakout and BPM electronics, output to PSC

c. Power Supply Controller.



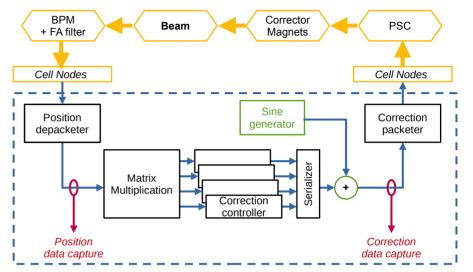


Same current algorithm

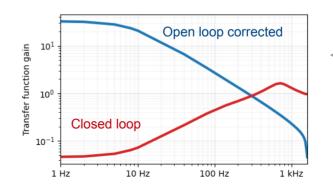
- Orbit Response Matrix inversed with SVD, Tikhonov regularization
- Correction controller is an 8 Hz low-pass filter (Perturbation attenuated by inverse of this filter)

Added functionnalities

- Add a per PSC sine signal
- Triggered data capture



Blue dashed rectangle: Central Node detailed correction algorithm. Yellow blocks show the complete loop



< Simulation of Transfer function Gain Input: sine generator Output: correction controller



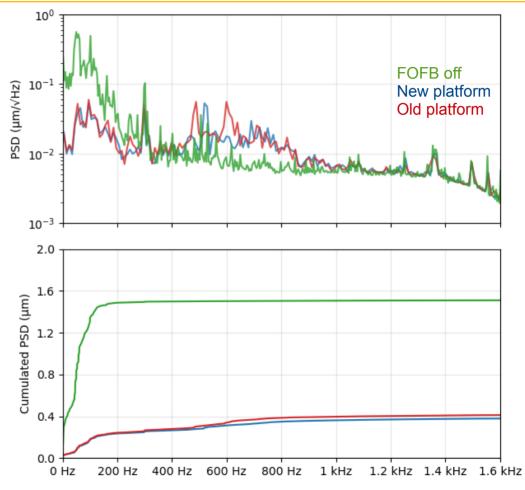


Test results



Machine tests

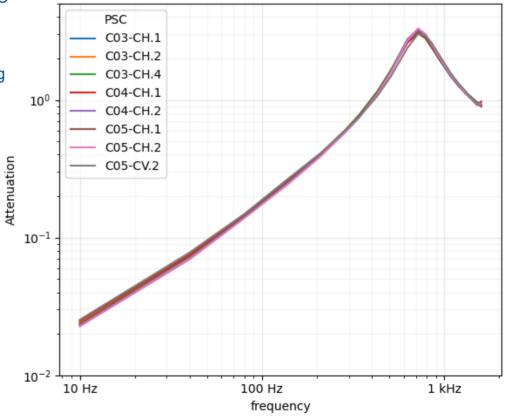
- Loop successfully closed ! Beam successfully accumulated up to 450 mA with the new platform running the FOFB
- Mean orbit position PSD x-plane, 450 mA stored beam.
 → Same performances reached.
- Latency slightly decreased: resonance overshoot moved to higher frequencies





Efficiency measurement

- Use on-board sine generator to inject perturbation on one PSC
- Compute Discrete Time Fourier Transform (DTFT) of mean orbit at this frequency
- Repeat at several frequencies, with and without FOFB running
- Compute attenuation factor: 5 at 100 Hz, overshoot crossover at 400 Hz





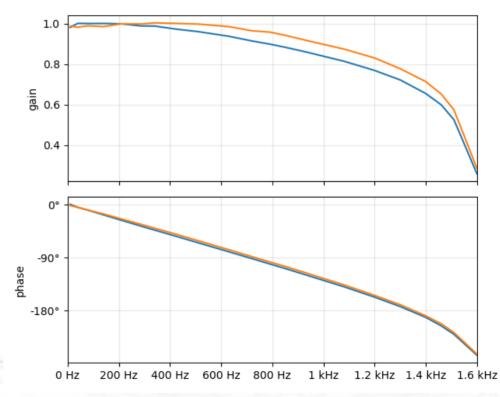


New identification features



Transfer function identification

- Open loop measurement: corrector not running
- Transfer Function of the overall system: PSC \rightarrow CM \rightarrow Beam \rightarrow BPM
- Driving 1 PSC at different frequencies. Capture 100 periods of data.
- Discrete Time Fourier Transform (DTFT) at each frequency.
 → Obtain TF module and phase
- BPM/PSC gain depends on the ORM
- Select and mean on 10 most significant BPM. Further normalize by gain at 210Hz.



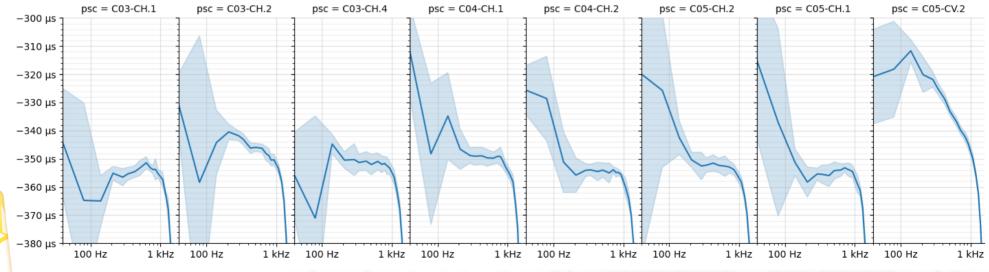
Bode plot of the measured transfer function. Blue and orange are one horizontal and one vertical PSC respectively.



Transfer function identification

Delay observation

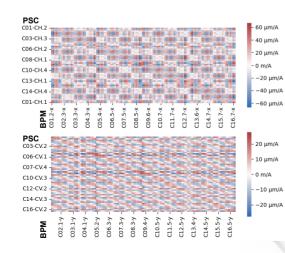
- Measured Constant latency of ~ 354/332 µs (X/Y plane)
- At low frequencies: measure uncertainty due to spectral occupation At high frequencies: phase shift
- The only Y PSC tested shows a phase shift. We will investigate this behavior on other Y PSC.
- Difference X/Y probably due to the vacuum chamber geometry.

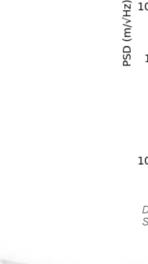


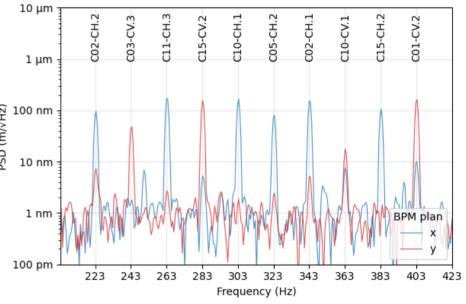
Observing delay vs frequency by PSC. Mean delay with ±std band.



- Open loop measurement: corrector not running
- Driving 10 PSC at 10 different frequencies, 20 Hz spaced
- Perform 10 group captures \rightarrow get the 100 PSC
- DTFT at each frequency: obtain module and phase
- Deduce ORM coefficients
- Overall capture takes < 2 minutes



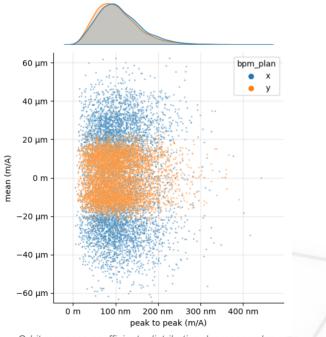


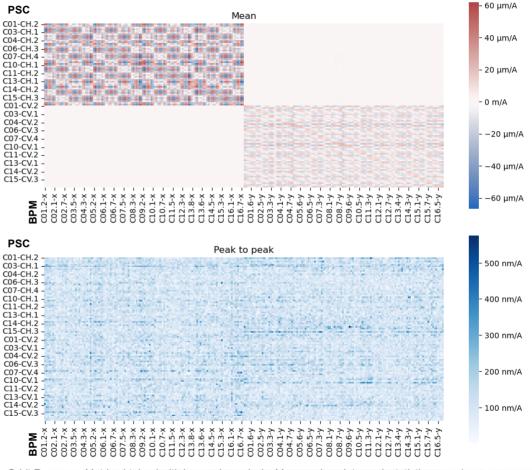


Driving ten PSCs with different frequencies, observing mean PSC over all BPMs. Sampling 10 kHz, duration 1.5 s, blackman window.



- Repeatability over 4 measures
- Different frequencies, PSC distributions
- Max peak to peak = 440 nm/A
- Repeatability will be compared to present DC method





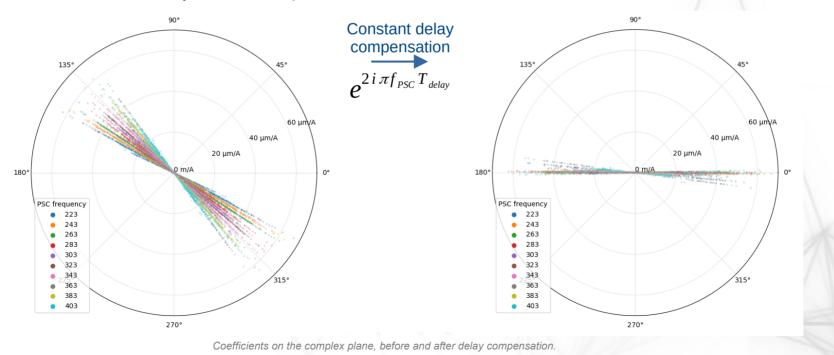
Orbit Response Matrix obtained with harmonic analysis. Mean and peak to peak statistics over 4 measures.

Orbit response coefficients distribution, by mean value and peak to peak statistics over 4 measures.

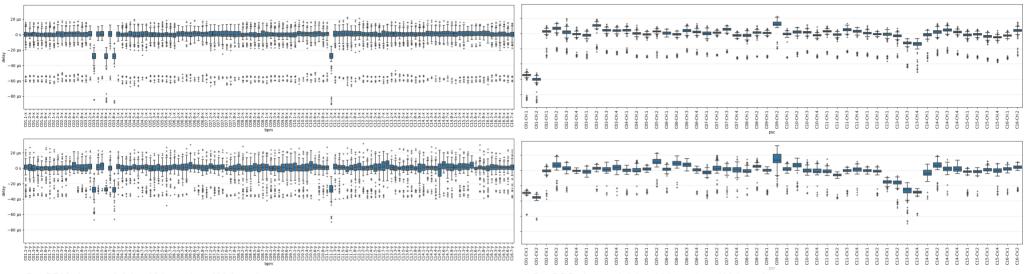


Measurement corrections

- on angle: compensate constant delay: 354/332 µs (X/Y plane) Angle of complex coefficient depends to delay and PSC frequency This is another way to measure constant delay
- on module: non constant Transfer Function over the frequency band of measurement. Each PSC TF estimated by a 1st order slope







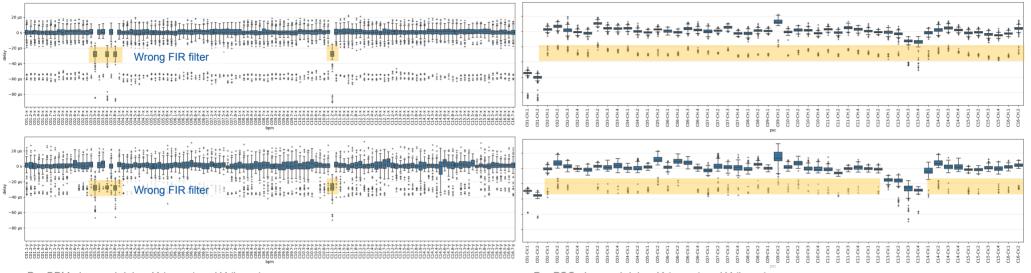
Per BPM observed delay, X (upper) and Y (lower)

Per PSC observed delay, X (upper) and Y (lower)

• Observing per BPM and per PSC delay offset from 354/332 µs (X/Y plane)





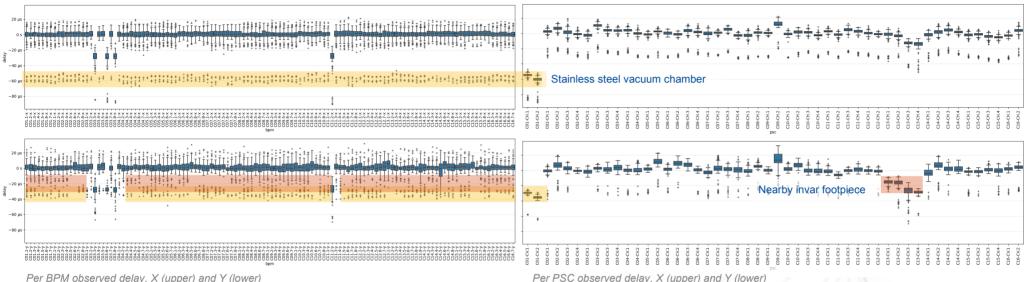


Per BPM observed delay, X (upper) and Y (lower)

Per PSC observed delay, X (upper) and Y (lower)

- Observing per BPM and per PSC delay offset from 354/332 µs (X/Y plane)
- 4 BPMs outliers spotted and corrected (wrong FIR filter)





Per BPM observed delay, X (upper) and Y (lower)

- Observing per BPM and per PSC delay offset from 354/332 µs (X/Y plane)
- 4 BPMs outliers spotted and corrected (wrong FIR filter)
- Some PSC show additional latency

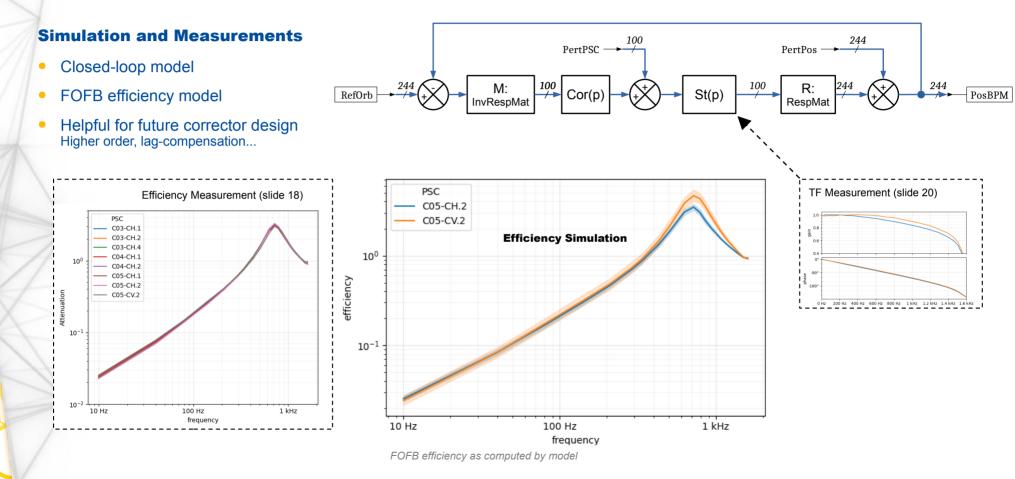
 \rightarrow C01 Injection zone, Corrector Magnets over stainless steel vacuum chamber

- \rightarrow C13 Corrector Magnets nearby Invar bpm footpiece
- We will further investigate these PSC with a full Transfer function identification





From identification to loop model







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- Loop successfully closed and performances reached
- **New features** to help diagnostics, identifications and future developments
- Next step: deploy the Control System devices to allow daily operation (SOFB / FOFB interaction)

Thank you for your attention